

NEW EXACT AND NUMERICAL SOLUTIONS OF FRACTIONAL KAUP-KUPERSHMIDT EQUATION

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ABSTRACT. In this article, the tanh method and the residual power series method (RPSM) are used to obtain new exact and numerical solutions of the time-fractional Kaup-Kupershmidt equation using the conformable fractional derivative definition. This definition is simple, effective and reliable in the solution procedure of the fractional differential equations that have complicated solutions with classical fractional derivative definitions like Caputo and Rieman-Liouville.

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1. INTRODUCTION

Fractional calculus has found numerous applications in science and engineering branches such as fractional differential equations (FDE), fluid flow, electrical network, mathematical physics, biology, image and signal processing, viscoelasticity and control in recent years.

There are some common methods that are used to obtain approximate or analytical solutions of nonlinear fractional partial differential equations in literature. Adomian decomposition method (ADM) [19], Laplace analysis method (LAM) [13], homotopy analysis method (HAM) [16], homotopy perturbation method (HPM) [22], differential transformation method (DTM) [5] and perturbation-iteration algorithm (PIA) [20] are among them.

In this article, the tanh method [8,21] and residual power series method (RPSM) [2,4,11,12,15] are used to obtain new exact and approximate solutions of time-fractional Kaup-Kumershmidt equation of the form

$$(1.1) \quad \frac{\partial^\alpha u}{\partial t^\alpha} + 45u^2 \frac{\partial u}{\partial x} - 15p \frac{\partial u}{\partial x} \frac{\partial^2 u}{\partial x^2} - 15u \frac{\partial^3 u}{\partial x^3} + \frac{\partial^5 u}{\partial x^5} = 0$$

The tanh method is a powerful tool for obtaining traveling wave solutions of nonlinear fractional differential equations. In this method a power series in tanh was used as an ansatz to obtain analytical solutions of traveling

wave type of certain evolution equations. Besides, in RPSM, the coefficients of the power series are calculated by means of the concept of residual error with the help of one or more variable algebraic equation chains, and finally, a so-called truncated series solution is obtained [15].

The major improvement of the RPSM is that it can be implemented to the problem directly without linearization, perturbation or discretization and without any transformation by selecting appropriate initial conditions [12].

After giving brief descriptions of tanh method and RSPM, we have presented one example that shows reliability and efficiency of two methods. Also figures and a table are presented in order to compare their numerical results. At last, we discussed about obtained results as a section for conclusion.

2. PRELIMINARIES

There are a few definition of fractional derivative of order $\alpha > 0$. The most widely used are the Riemann-Liouville and Caputo fractional derivatives.

Definition 2.1. The Riemann-Liouville fractional derivative operator $D^\alpha f(x)$ for $\alpha > 0$ and $q - 1 < \alpha < q$ defined as [2,9,10]:

$$(2.1) \quad D^\alpha f(x) = \frac{d^q}{dx^q} \left[\frac{1}{\Gamma(q-\alpha)} \int_{\alpha}^x \frac{f(t)}{(x-t)^{\alpha+1-q}} dt \right]$$

Definition 2.2. The Caputo fractional derivative of order $\alpha > 0$ for $n \in \mathbb{N}$, $n - 1 < \alpha < n$, D_*^α , defined as [7]:

$$(2.2) \quad D_*^\alpha f(x) = J^{n-\alpha} D^n f(x) = \frac{1}{\Gamma(n-\alpha)} \int_{\alpha}^x (x-t)^{n-\alpha-1} \left(\frac{d}{dt} \right)^n f(t) dt$$

Recently, a new definition of a fractional derivative called the "conformable fractional derivative" has been proposed by R. Khalil et al. [6].

Definition 2.3. Let $f : [0, \infty) \rightarrow \mathbb{R}$ is a function α -th order "conformable fractional derivative" of a defined by

$$(2.3) \quad T_\alpha(f)(t) = \lim_{\varepsilon \rightarrow 0} \frac{f(t + \varepsilon t^{1-\alpha}) - (f)(t)}{\varepsilon}$$

for all $t > 0$, $\alpha \in (0, 1)$.

The properties of this new definition are given in the following theorem [14]

Theorem 2.1. Let $\alpha \in (0, 1]$ and f, g functions are α -differentiable at point $t > 0$, then

1. $T_\alpha(mf + ng) = mT_\alpha(f) + nT_\alpha(g)$ for all $m, n \in \mathbb{R}$
2. $T_\alpha(t^p) = pt^{p-\alpha}$ for all p
3. $T_\alpha(f \cdot g) = fT_\alpha(g) + gT_\alpha(f)$
4. $T_\alpha\left(\frac{f}{g}\right) = \frac{gT_\alpha(f) - fT_\alpha(g)}{g^2}$
5. $T_\alpha(c) = 0$ for all constant functions $f(t) = c$
6. If, in addition, f is differentiable, then $T_\alpha(f)(t) = t^{1-\alpha} \frac{df(t)}{dt}$

Definition 2.4. Let f is a function with n variables x_1, \dots, x_n , and the conformable partial derivatives of f of order $\alpha \in (0, 1]$ in x_i is defined as follows [6]

$$(2.4) \quad \frac{d^\alpha}{dx_i^\alpha} f(x_1, \dots, x_n) = \lim_{\varepsilon \rightarrow 0} \frac{f(x_1, \dots, x_{i-1}, x_i + \varepsilon x_i^{1-\alpha}, \dots, x_n) - f(x_1, \dots, x_n)}{\varepsilon}.$$

Definition 2.5. The conformable integral of a function f starting from $a \geq 0$ is defined as [16]

$$(2.5) \quad I_\alpha^a(f)(s) = \int_a^s \frac{f(t)}{t^{1-\alpha}} dt.$$

3. A BRIEF DESCRIPTION OF IMPLEMENTED METHODS

3.1. The Tanh Method.

In the beginning we are going to describe the method [21] incrementally.

Step1. The general form of nonlinear conformable fractional differential equation can be regarded as

$$(3.1) \quad P\left(\frac{\partial^\alpha u}{\partial t^\alpha}, \frac{\partial u}{\partial x}, \frac{\partial^{2\alpha} u}{\partial t^{2\alpha}}, \frac{\partial^2 u}{\partial x^2}, \dots\right) = 0$$

where the arguments and subscripts of polynomial P shows partial derivatives.

Step2. Employing the transformation

$$(3.2) \quad u(x, t) = u(\xi), \quad \xi = kx - m \frac{t^\alpha}{\alpha}$$

in which k denotes the number of wave and m shows the velocity of the wave. Due to this:

$$(3.3) \quad \frac{\partial^\alpha(\cdot)}{\partial t^\alpha} = n \frac{d(\cdot)}{d\xi}, \quad \frac{\partial(\cdot)}{\partial x} = m \frac{d(\cdot)}{d\xi}, \dots$$

Considering Eq.(3.2), Eq.(3.1) turns in to a differential equation

$$(3.4) \quad G(U, U', U'', U''', \dots) = 0$$

where the derivatives are with respect to ξ .

Step3. Now, describing a new independent variable

$$(3.5) \quad Y = \tanh(\xi).$$

Then the following equations are hold.

$$(3.6) \quad \begin{aligned} \frac{\partial}{\partial \xi} &= (1 - Y^2) \frac{\partial}{\partial Y}, \\ \frac{\partial^2}{\partial \xi^2} &= -2Y(1 - Y^2) \frac{\partial}{\partial Y} + (1 - Y^2)^2 \frac{\partial^2}{\partial Y^2}, \\ \frac{\partial^3}{\partial \xi^3} &= 2(1 - Y)^2(3Y^2 - 1) \frac{\partial}{\partial Y} - 6Y(1 - Y^2)^2 \frac{\partial^2}{\partial Y^2} + ((1 - Y^2)^3) \frac{\partial^3}{\partial Y^3}, \end{aligned}$$

$$\frac{\partial^4}{\partial \xi^4} = -8Y(1 - Y^2)(3Y^2 - 2) \frac{\partial}{\partial Y} + 4(1 - Y^2)^2(9Y^2 - 2) \frac{\partial^2}{\partial Y^2} - 12Y(1 - Y^2)^3 \frac{\partial^3}{\partial Y^3} + (1 - Y^2)^4 \frac{\partial^4}{\partial Y^4},$$

$$\begin{aligned} \frac{\partial^5}{\partial \xi^5} = & -8Y(-1+Y^2)(2-15Y^2+15Y^4)\frac{\partial}{\partial Y} - 120Y(-1+Y^2)^2(-1+2Y^2)\frac{\partial^2}{\partial Y^2} \\ & - 20(-1+Y^2)^3(-1+6Y^2)\frac{\partial^3}{\partial Y^3} - 20Y(-1+Y^2)^4\frac{\partial^4}{\partial Y^4} + (1-Y^2)^5\frac{\partial^5}{\partial Y^5}. \end{aligned}$$

Step4. Present the prediction

$$(3.7) \quad U(\xi) = S(Y) = \sum_{i=0}^r a_i Y^i$$

where r is a positive integer, in most cases, that will be evaluated. Substituting (3.7) into the ODE (3.4) concludes an equation in powers of Y .

Step5. Balancing the linear terms of highest order in the ODE (3.4) with the highest order nonlinear terms gives us the parameter r . After obtaining r , the all coefficients of Y are equated to zero in the resulting equation. This results a system of algebraic equations including k, m, p and $a_i, (i = 0, 1, \dots, r)$. The analytical solution is obtained in a closed form after having determined these parameters, considering that r is a positive integer, and using (3.7).

To be very competent on the the tanh method, one can look into Ref. [17, 18] for the analysis with useful discussions.

3.2. Description of the residual power series method.

In this section we are going to introduce some important definitions and theorems about residual power series

Theorem 3.1. Suppose that f has a FPS representation at $t_0 = 0$ of the form

$$(3.8) \quad f(t) = \sum_{n=0}^{\infty} c_n t^{n\alpha}, 0 < t < R^{\frac{1}{\alpha}}, R > 0$$

where $R^{\frac{1}{\alpha}}$ is the radius of convergence. If f is an infinitely conformable α -differentiable function, for some $0 \leq m-1 < \alpha \leq m$ in a neighborhood of a point $t_0 = 0$, then the coefficients c_n in (3.8) will take the form $c_n = \frac{f^{(n\alpha)}(0)}{\alpha^n n!}$ where $f^{(n\alpha)}(t)$ means the application of the conformable fractional derivative n times [1].

Definition 3.1. A multiple fractional power series about $t_0 = 0$ is defined by $\sum_{n=0}^{\infty} f_n(x)t^{n\alpha}$, where $f_n(x)$ are the coefficients of the series depend on x and t is a variable.

Definition 3.2. A power series of the form $\sum_{n=0}^{\infty} f_n(x)t^{n\alpha}$, is called a multiple fractional power series about $t_0 = 0$, where t is a variable and $f_n(x)$ are functions of x called the coefficients of the series [11].

Theorem 3.2. Assume that $u(x, t)$ has a multiple fractional power series representation at $t_0 = 0$ of the form [3]

$$(3.9) \quad u(x, t) = \sum_{n=0}^{\infty} f_n(x)t^{n\alpha}, 0 \leq m-1 < \alpha < m, x \in I, 0 \leq t \leq R^{\frac{1}{\alpha}}.$$

If $u_t^{(n\alpha)}(x, t), n = 0, 1, 2, \dots$ are continuous on $I \times (0, R^{\frac{1}{\alpha}})$, then $f_n(x) = \frac{u_t^{(n\alpha)}(x, 0)}{\alpha^n n!}$.

To clarify the basic concept of RPSM, let's take a nonlinear fractional differential equation of the form:

$$(3.10) \quad T_{\alpha} u(x, t) + N[x]u(x, t) + R[x]u(x, t) = c(x, t), x \in \mathbb{R}, n-1 < n\alpha \leq n, t > 0$$

expressed by initial condition

$$(3.11) \quad f_0(x) = u(x, 0) = f(x)$$

where $R[x]$ is a linear, $N[x]$ is a non-linear operator and $c(x, t)$ are continuous functions.

The RPSM method made up of stating the solution of the equation (3.10) subject to (3.11) as a fractional power series expansion around $t = 0$.

$$(3.12) \quad f_{(n-1)}(x) = T_t^{(n-1)\alpha} u(x, 0) = h(x)$$

The expansion form of the solution is given by

$$(3.13) \quad u(x, t) = f(x) + \sum_{n=0}^{\infty} f_n(x) \frac{t^{n\alpha}}{\alpha^n n!}$$

In the next step, the k -truncated series of $u(x, t)$, namely $u_k(x, t)$ can be written as:

$$(3.14) \quad u_k(x, t) = f(x) + \sum_{n=0}^k f_n(x) \frac{t^{n\alpha}}{\alpha^n n!}$$

If the 1. RPS approximate solution $u_1(x, t)$ is

$$(3.15) \quad u_1(x, t) = f(x) + f_1(x) \frac{t^\alpha}{\alpha^n}$$

then $u_k(x, t)$ could be reformulated as

$$(3.16) \quad u_k(x, t) = f(x) + f_1(x) \frac{t^\alpha}{\alpha^n} + \sum_{n=2}^k f_n(x) \frac{t^{n\alpha}}{\alpha^n n!}$$

for $0 < \alpha \leq 1$, $0 \leq t < \mathbb{R}^{\frac{1}{\alpha}}$, $x \in I$ and $k = 2, 3, 4, \dots$

First we express the residual function as

$$(3.17) \quad Res(x, t) = T_\alpha u(x, t) + N[x]u(x, t) + R[x]u(x, t) - c(x, t)$$

and the k -residual function as

$$(3.18) \quad Res_k(x, t) = T_\alpha u_k(x, t) + N[x]u_k(x, t) + R[x]u_k(x, t) - g(x, t), \quad k = 1, 2, 3, \dots$$

It is clear that $Res(x, t) = 0$ and $\lim_{k \rightarrow \infty} Res_k(x, t) = Res(x, t)$ for each $x \in I$ and $0 \leq t$. In fact this lead to $\frac{\partial^{(n-1)\alpha}}{\partial t^{(n-1)\alpha}} Res_k(x, t)$ for $n = 1, 2, 3, \dots, k$ because in the conformable sense, the fractional derivative of a constant is zero [4, 12, 15]. Solving the equation $\frac{\partial^{(n-1)\alpha}}{\partial t^{(n-1)\alpha}} Res_k(x, 0) = 0$ gives us the desired $f_n(x)$ coefficients. Thus the $u_n(x, t)$ approximate solutions can be obtained respectively.

4. APPLICATION OF METHODS FOR SOLVING FRACTIONAL KAUP-KUPERSHMITZ EQUATION

4.1. Application of Tanh Method.

Regard the conformable time-fractional Kaup-Kupershmidt equation

$$(4.1) \quad \frac{\partial^\alpha u}{\partial t^\alpha} + 45u^2 \frac{\partial u}{\partial x} - 15p \frac{\partial u}{\partial x} \frac{\partial^2 u}{\partial x^2} - 15u \frac{\partial^3 u}{\partial x^3} + \frac{\partial^5 u}{\partial x^5} = 0$$

where $\alpha \in (0, 1)$. Using the wave transform (3.2) and (3.3), the equation (4.1) becomes

$$(4.2) \quad -mu' + 45ku^2u' - 15k^3pu'u'' - 15k^3u'u''' + k^5u^{(5)}$$

where the prime symbolizes the derivation with respect to ξ . Then using the ansatz

$$(4.3) \quad Y = \tanh(\xi)$$

and

$$(4.4) \quad u = S(Y) = \sum_{i=0}^r a_i Y^i$$

When we balance the highest order linear terms in the resulting equation with the highest order nonlinear terms in Eq. (4.2), we obtain $r = 2$ and using (4.4) and (3.6) in resulting equation we get

$$(4.5) \quad \begin{aligned} & -m(1-Y^2) \frac{dS}{dY} + 45kS^2(1-Y^2) \frac{dS}{dY} - 15k^3p(1-Y^2) \frac{dS}{dY} \left(-2Y(1-Y^2) \frac{dS}{dY} + (1-Y^2)^2 \frac{d^2S}{dY^2} \right) \\ & - 15k^3S \left(2(1-Y^2)(3Y^2-1) \frac{dS}{dY} - 6Y(1-Y^2)^2 \frac{d^2S}{dY^2} \right) + k^5(-8(-1+Y^2)(2-15Y^2+15Y^4) \frac{dS}{dY} \\ & - 120Y(-1+Y^2)^2(-1+2Y^2) \frac{d^2S}{dY^2}) = 0. \end{aligned}$$

Using obtained values in (4.4), subrogating into (4.5), equating all coefficients of Y led to an algebraic equation system for a_0, a_1, a_2, k, m as follows.

$$\begin{aligned} & 45a_0^2a_1k + 30a_0a_1k^3 + 16a_1k^5 - a_1m - 30a_1a_2k^3p = 0, \\ & 90a_0a_1^2k + 90a_0^2a_2k + 30a_1^2k^3 + 240a_0a_2k^3 + 272a_2k^5 - 2a_2m + 30a_1^2k^3p - 60a_2^2k^3p = 0, \\ & -45a_0^2a_1k + 45a_1^3k + 270a_0a_1a_2k - 120a_0a_1k^3 + 270a_1a_2k^3 - 136a_1k^5 + a_1m + 210a_1a_2k^3p = 0, \\ & -90a_0a_1^2k - 90a_0^2a_2k + 180a_1^2a_2k + 180a_0a_2^2k - 120a_1^2k^3 - 600a_0a_2k^3 + 240a_2^2k^3 \\ & - 1232a_2k^5 + 2a_2m - 60a_1^2k^3p + 300a_2^2k^3p = 0, \\ & -45a_1^3k - 270a_0a_1a_2k + 225a_1a_2^2k + 90a_0a_1k^3 - 720a_1a_2k^3 + 240a_1k^5 - 330a_1a_2k^3p = 0, \\ & -180a_1^2a_2k - 180a_0a_2^2k + 90a_2^3k + 90a_1^2k^3 + 360a_0a_2k^3 - 600a_2^2k^3 + 1680a_2k^5 + 30a_1^2k^3p - 420a_2^2k^3p = 0, \\ & -225a_1a_2^2k + 450a_1a_2k^3 - 120a_1k^5 + 150a_1a_2k^3p = 0, \\ & -90a_2^3k + 360a_2^2k^3 - 720a_2k^5 + 180a_2^2k^3p = 0. \end{aligned}$$

Solving this system with aid of Mathematica we get two solution set

Set 1:

$$\begin{aligned}
 m &= 2 \left(-12k^5 + 10k^5p + 5k^5p^2 - 5k^3p\sqrt{k^4(-4+4p+p^2)} \right), \\
 a_0 &= \frac{2}{3} \left(-2k^2 - k^2p + \sqrt{k^4(-4+4p+p^2)} \right), \\
 a_1 &= 0, \\
 a_2 &= 2k^2 + k^2p - \sqrt{-4k^4 + 4k^4p + k^4p^2}.
 \end{aligned}
 \tag{4.6}$$

Thus using (3.2), (4.3), (4.4) and (4.6) the exact solutions can be found as

$$\begin{aligned}
 u_1(x, t) &= \frac{2}{3} \left(-2k^2 - k^2p + \sqrt{k^4(-4+4p+p^2)} \right) \\
 &+ \left(2k^2 + k^2p - \sqrt{-4k^4 + 4k^4p + k^4p^2} \right) \tanh \left[kx - \frac{2 \left(-12k^5 + 10k^5p + 5k^5p^2 - 5k^3p\sqrt{k^4(-4+4p+p^2)} \right) t^\alpha}{\alpha} \right]^2.
 \end{aligned}$$

Set 2:

$$\begin{aligned}
 m &= 2 \left(-12k^5 + 10k^5p + 5k^5p^2 + 5k^3p\sqrt{k^4(-4+4p+p^2)} \right), \\
 a_0 &= \frac{2}{3} \left(-2k^2 - k^2p - \sqrt{k^4(-4+4p+p^2)} \right), \\
 a_1 &= 0, \\
 a_2 &= 2k^2 + k^2p + \sqrt{-4k^4 + 4k^4p + k^4p^2},
 \end{aligned}
 \tag{4.8}$$

Hence again using (3.2), (4.3), (4.4) and (4.7) the analytical solutions can be found as

$$\begin{aligned}
 u_2(x, t) &= \frac{2}{3} \left(-2k^2 - k^2p - \sqrt{k^4(-4+4p+p^2)} \right) \\
 &+ \left(2k^2 + k^2p + \sqrt{-4k^4 + 4k^4p + k^4p^2} \right) \tanh \left[kx - \frac{2 \left(-12k^5 + 10k^5p + 5k^5p^2 + 5k^3p\sqrt{k^4(-4+4p+p^2)} \right) t^\alpha}{\alpha} \right]^2.
 \end{aligned}$$

4.2. Application of Residual Power Series Method. Consider the nonlinear time fractional Kaup-Kupersmidt equation

$$\frac{\partial^\alpha u}{\partial t^\alpha} + 45u^2 \frac{\partial u}{\partial x} - 15p \frac{\partial u}{\partial x} \frac{\partial^2 u}{\partial x^2} - 15u \frac{\partial^3 u}{\partial x^3} + \frac{\partial^5 u}{\partial x^5} = 0
 \tag{4.10}$$

with the initial conditions obtained from the exact solution

$$u(x, 0) = \frac{2}{3} \left(-2k^2 - k^2p + \sqrt{k^4(-4+4p+p^2)} \right) + \left(2k^2 + k^2p - \sqrt{-4k^4 + 4k^4p + k^4p^2} \right) \tanh[kx]^2
 \tag{4.11}$$

The exact solution of time fractional Kaup-Kupersmidt equation is taken as (4.7)

For residual power series

$$u(x, t) = f(x) + \sum_{n=0}^{\infty} f_n(x) \frac{t^{n\alpha}}{\alpha^n n!}
 \tag{4.12}$$

and k .truncated series of $u(x, t)$

$$(4.13) \quad u_k(x, t) = f(x) + \sum_{n=0}^k f_n(x) \frac{t^{n\alpha}}{\alpha^n n!}, k = 1, 2, 3, \dots$$

The k_1 th residual function of time fractional Kaup-Kupershmidt equation is:

$$(4.14) \quad Resu_k(x, t) = \frac{\partial^\alpha u_k}{\partial t^\alpha} + 45u_k^2 \frac{\partial u_k}{\partial x} - 15p \frac{\partial u_k}{\partial x} \frac{\partial^2 u_k}{\partial x^2} - 15u_k \frac{\partial^3 u_k}{\partial x^3} + \frac{\partial^5 u_k}{\partial x^5}$$

to determine the coefficient $f_1(x)$, in $u_k(x, t)$, we should subrogate the 1.th truncated series $u_1(x, t) = f(x) + f_1(x) \frac{t^\alpha}{\alpha}$ into the 1st truncated residual function

$$(4.15) \quad Resu_1(x, t) = \frac{\partial^\alpha u_1}{\partial t^\alpha} + 45u_1^2 \frac{\partial u_1}{\partial x} - 15p \frac{\partial u_1}{\partial x} \frac{\partial^2 u_1}{\partial x^2} - 15u_1 \frac{\partial^3 u_1}{\partial x^3} + \frac{\partial^5 u_1}{\partial x^5}$$

Now for the substitution of $t = 0$ through equation $Resu_1(x, t)$ to obtain

$$(4.16) \quad Resu_1(x, 0) = f_1(x) + 45f^2(x)f'(x) - 15pf'(x)f''(x) - 15f(x)f^{(3)}(x) + f^{(5)}(x)$$

Thus for $Res_1(x, 0) = 0$

$$(4.17) \quad f_1(x) = -45f^2(x)f'(x) + 15pf'(x)f''(x) + 15f(x)f^{(3)}(x) - f^{(5)}(x)$$

Therefore, we obtain the 1st RPS approximate solution of time-fractional Kaup-Kupershmidt equation as

$$(4.18) \quad u_1(x, t) = f(x) + \frac{1}{\alpha} t^\alpha (-45f^2(x)f'(x) + 15pf'(x)f''(x) + 15f(x)f^{(3)}(x) - f^{(5)}(x))$$

Again, to determine the second unknown coefficient $f_2(x)$, we subrogate the 2nd truncated series solution $u_2(x, t) = f(x) + f_1(x) \frac{t^\alpha}{\alpha} + f_2(x) \frac{t^{2\alpha}}{2\alpha^2}$ into the 2nd truncated residual function

$$(4.19) \quad Resu_2(x, t) = \frac{\partial^\alpha u_2}{\partial t^\alpha} + 45u_2^2 \frac{\partial u_2}{\partial x} - 15p \frac{\partial u_2}{\partial x} \frac{\partial^2 u_2}{\partial x^2} - 15u_2 \frac{\partial^3 u_2}{\partial x^3} + \frac{\partial^5 u_2}{\partial x^5}$$

to obtain

$$(4.20) \quad \begin{aligned} Resu_2(x, t) = & 45 \left(f(x) + \frac{t^\alpha f_1(x)}{\alpha} + \frac{t^{2\alpha} f_2(x)}{2\alpha^2} \right) \left(f'(x) + \frac{t^\alpha f_1'(x)}{\alpha} + \frac{t^{2\alpha} f_2'(x)}{2\alpha^2} \right) \\ & - 15p \left(f'(x) + \frac{t^\alpha f_1'(x)}{\alpha} + \frac{t^{2\alpha} f_2'(x)}{2\alpha^2} \right) \left(f''(x) + \frac{t^\alpha f_1''(x)}{\alpha} + \frac{t^{2\alpha} f_2''(x)}{2\alpha^2} \right) \\ & - 15 \left(f(x) + \frac{t^\alpha f_1(x)}{\alpha} + \frac{t^{2\alpha} f_2(x)}{2\alpha^2} \right) \left(f^{(3)}(x) + \frac{t^\alpha f_1^{(3)}(x)}{\alpha} + \frac{t^{2\alpha} f_2^{(3)}(x)}{2\alpha^2} \right) \\ & + f^{(5)}(x) + \frac{t^\alpha f_1^{(5)}(x)}{\alpha} + \frac{t^{2\alpha} f_2^{(5)}(x)}{2\alpha^2} \end{aligned}$$

Now, applying T_α on both sides of $Resu_2(x, t)$ and equating to 0 for $t = 0$ gives:

$$\begin{aligned}
 f_2(x) = & -90f(x)f_1(x)f'(x) - 45f^2(x)f_1'(x) + 15pf_1'(x)f''(x) \\
 (4.21) \quad & + 15pf'(x)f_1''(x) + 15f_1(x)f^{(3)}(x) + 15f(x)f_1^{(3)}(x) - f_1^{(5)}(x)
 \end{aligned}$$

Therefore the 2nd RPS approximate solution of time-fractional Kaup-Kupershmidt is obtained as:

$$\begin{aligned}
 u_2(x, t) = & f(x) + \frac{t^\alpha f_1(x)}{\alpha} + \frac{t^{2\alpha}}{2\alpha^2}(-90f(x)f_1(x)f'(x) - 45f^2(x)f_1'(x) + 15pf_1'(x)f''(x) \\
 (4.22) \quad & + 15pf'(x)f_1''(x) + 15f_1(x)f^{(3)}(x) + 15f(x)f_1^{(3)}(x) - f_1^{(5)}(x))
 \end{aligned}$$

In the same manner, we apply the same procedure for $n = 3$ to obtain the following results.

$$\begin{aligned}
 f_3(x) = & -90f^2(x)f'(x) - 90f(x)f_2(x)f'(x) - 180f(x)f_1(x)f_1'(x) - 45f^2(x)f_2'(x) + 15pf_2'(x)f''(x) \\
 (4.23) \quad & + 30pf_1'(x)f_1''(x) + 15pf'(x)f_2''(x) + 15f_2(x)f^{(3)}(x) + 30f_1(x)f_1^{(3)}(x) + f(x)f_2^{(3)}(x) - f_2^{(5)}(x)
 \end{aligned}$$

$$\begin{aligned}
 u_3(x, t) = & f(x) + \frac{t^\alpha f_1(x)}{\alpha} + \frac{t^{2\alpha} f_2(x)}{2\alpha^2} + \frac{t^{3\alpha}}{6\alpha^3}(-90f^2(x)f'(x) - 90f(x)f_2(x)f'(x) \\
 (4.24) \quad & - 180f(x)f_1(x)f_1'(x) - 45f^2(x)f_2'(x) + 15pf_2'(x)f''(x) + 30pf_1'(x)f_1''(x) \\
 & + 15pf'(x)f_2''(x) + 15f_2(x)f^{(3)}(x) + 30f_1(x)f_1^{(3)}(x) + f(x)f_2^{(3)}(x) - f_2^{(5)}(x))
 \end{aligned}$$

	$\alpha = 0.25$	$\alpha = 0.50$	$\alpha = 0.75$	$\alpha = 1$		
x	u_3	u_3	u_3	$RPSM$	$Exact$	$Absolute\ error$
0	-0.165431	-0.166569	-0.166653	-0.166664	-0.166664	1.58945E-11
0.1	-0.16656	-0.166438	-0.166214	-0.166118	-0.166118	1.55637E-11
0.2	-0.166442	-0.165064	-0.164536	-0.164335	-0.164335	1.45830E-11
0.3	-0.165082	-0.162474	-0.161652	-0.161350	-0.161350	1.30444E-11
0.4	-0.162504	-0.158718	-0.157618	-0.157222	-0.157222	1.10004E-11
0.5	-0.158761	-0.153869	-0.152513	-0.152028	-0.152028	8.67079E-12
0.6	-0.153924	-0.148018	-0.146429	-0.145866	-0.145866	6.11641E-12
0.7	-0.148083	-0.141269	-0.139477	-0.138844	-0.138844	3.52712E-12
0.8	-0.141344	-0.133740	-0.131774	-0.131083	-0.131083	1.02934E-12
0.9	-0.133824	-0.125555	-0.123446	-0.122708	-0.122708	1.25487E-12
1.0	-0.125646	-0.116841	-0.114621	-0.113846	-0.113846	3.22763E-12

TABLE 1. Comparison of numerical results for $\lambda = 0.1$, $\omega = 1$, $\mu = 0$, $t = 0.1$, $p = 2.5$ and $k = 0.5$ with different values of α .

5. CONCLUSION AND DISCUSSION

In this paper, exact and approximate solutions of the nonlinear time-fractional Kaup-Kupershmidt differential equation with the tanh method and residual power series method (RPSM) are obtained. With the help of conformable fractional derivative definition we can easily transform fractional differential equations to the known classical differential equations. By these methods and conformable fractional derivative definition, it is shown that there is no need another complex method and complex definition. Approximate and exact solutions of time-fractional Kaup-Kupershmidt differential equation are compared. Absolute errors are given with approximate

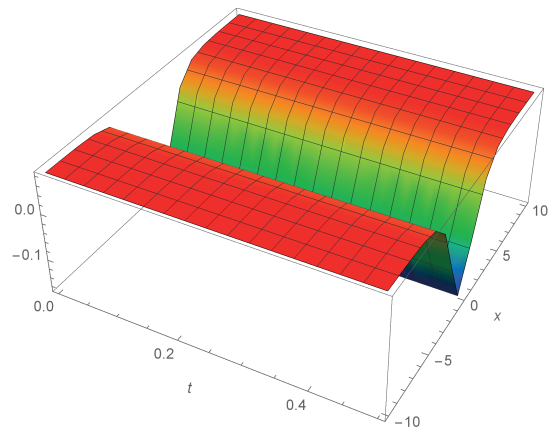
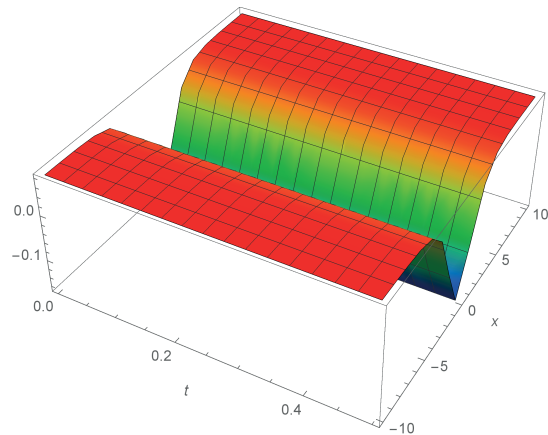
(A) RPSM solution for $\alpha = 1$.(B) Exact solution for $\alpha = 1$

FIGURE 1

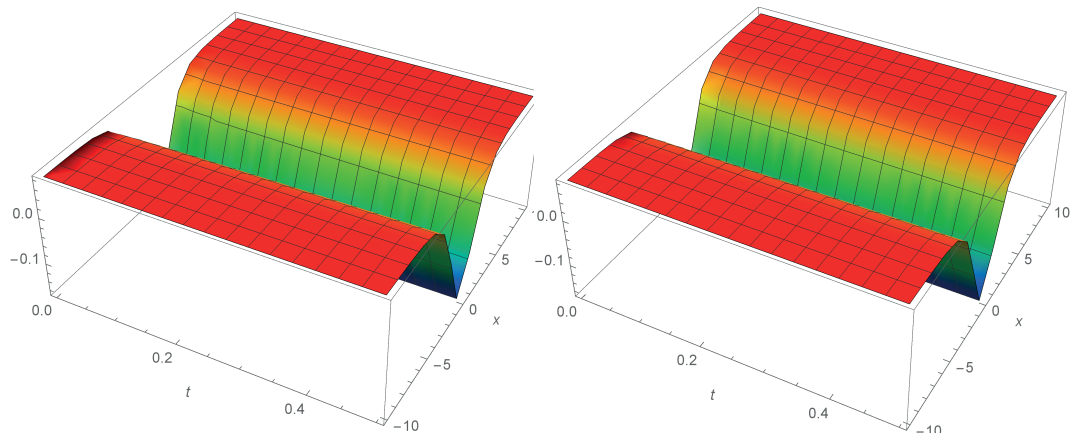
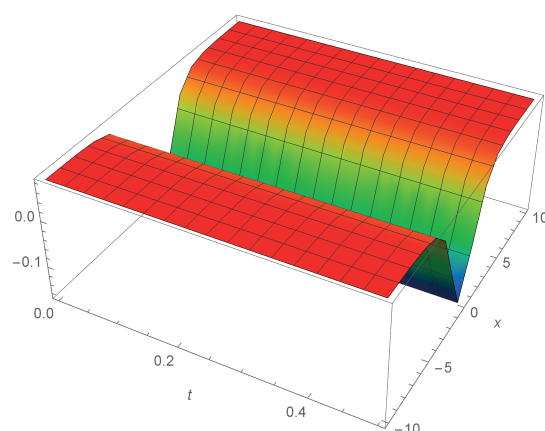
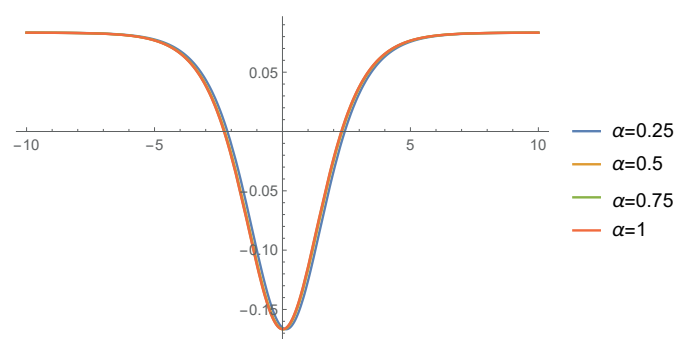
(A) RPSM solution for $\alpha = 0.25$.(B) RPSM solution for $\alpha = 0.50$

FIGURE 2

and exact solutions with the help of graphs and tables. Also, it is seen that conformable fractional derivative is clearer, simpler and understandable than other fractional derivative definitions.

FIGURE 3. RPSM solution for $\alpha = 0.75$.FIGURE 4. Plots of $u_3(x, t)$ versus space x for different values of α at $t = 0.1$.

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